

*For CS291-J00,
These slides are slightly edited versions of those available at:
<http://grail.cs.washington.edu/projects/slf/>*

Surface Light Fields for 3D Photography

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3D Photography



Goals

Rendering and editing

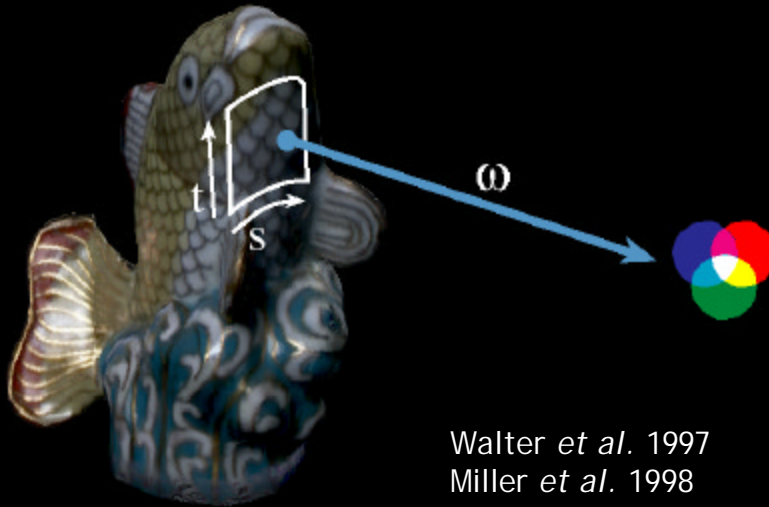
Inputs

Photographs and
geometry

Requirements

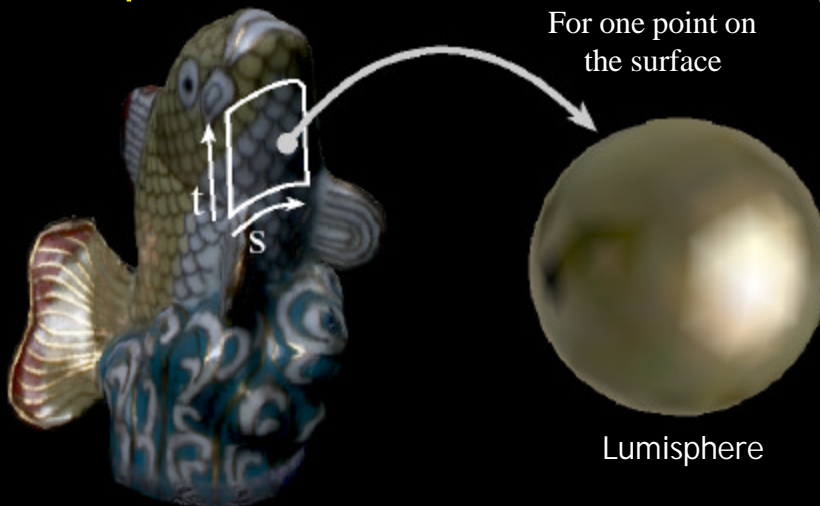
Estimation and
compression

Surface light fields



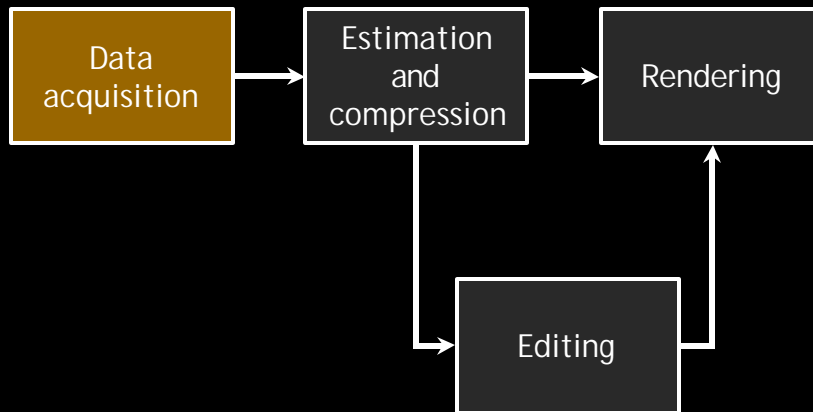
Walter *et al.* 1997
Miller *et al.* 1998
Nishino *et al.* 1999

Lumisphere-valued "texture" maps

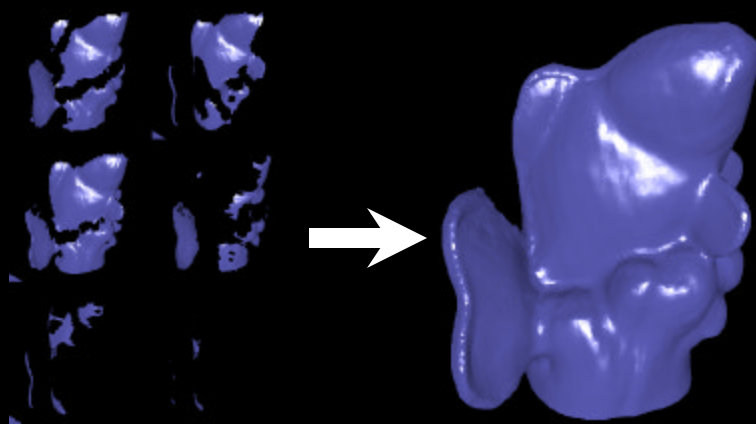


NOTE: Lighting remains fixed, and isn't controllable

Overview



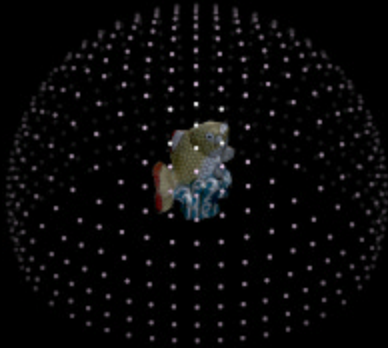
Scan and reconstruct geometry



Range scans
(only a few shown . . .)

Reconstructed geometry

Take photographs

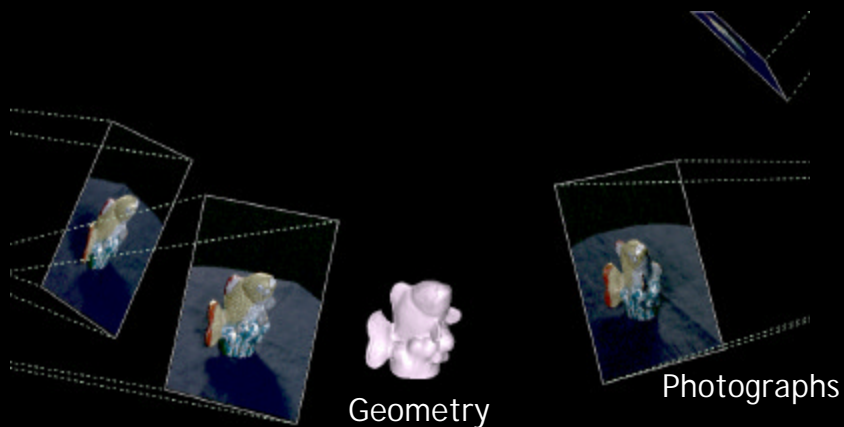


Camera positions



Photographs

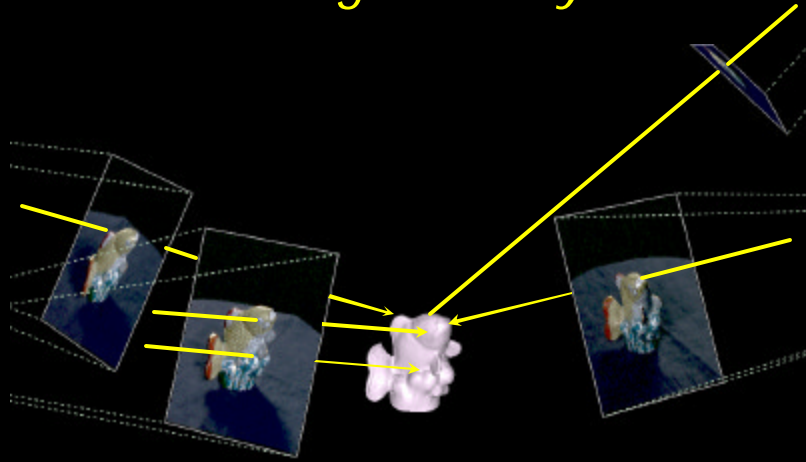
Register photographs to geometry



Geometry

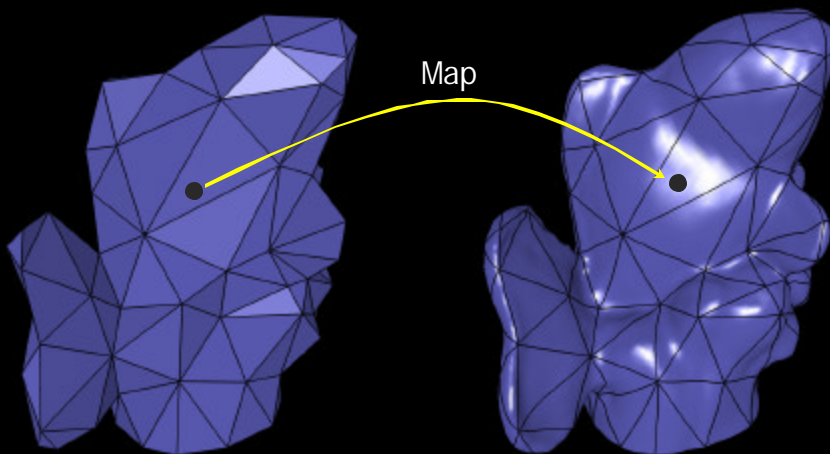
Photographs

Register photographs to geometry



User selected correspondences (rays)

Parameterizing the geometry Atlas of Charts

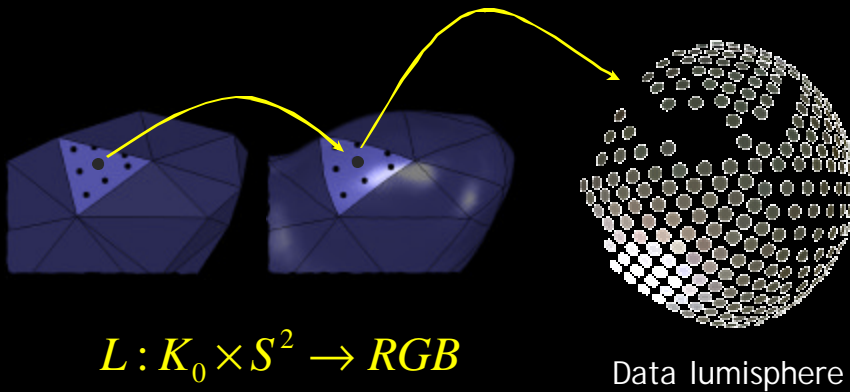


Base mesh

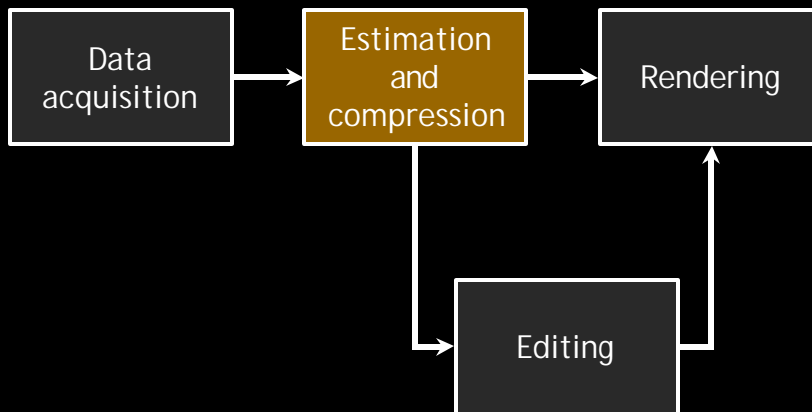
Scanned geometry

$$L: K_0 \rightarrow M \subset \mathcal{R}^3$$

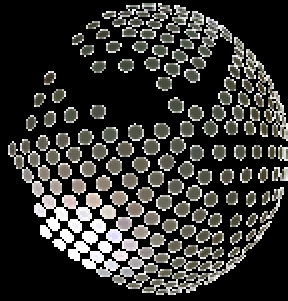
Assembling data lumispheres



Overview



Pointwise fairing
Interpolation, filling in missing data



Data lumisphere



Faired lumisphere

Pointwise fairing results

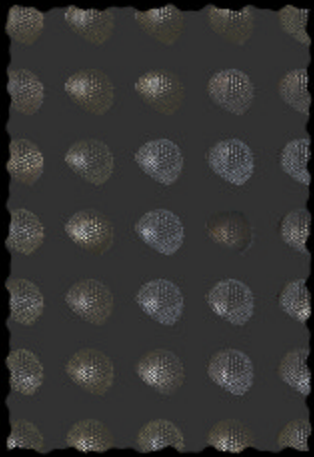


Input photograph



Pointwise faired
(177 MB)

Pointwise fairing

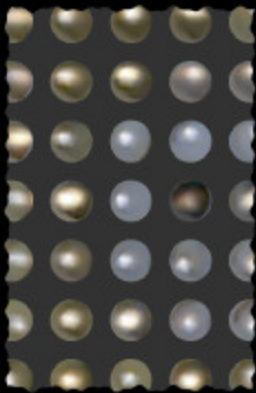


Many input data lumispheres



Many faired lumispheres

Compression



Many input data lumispheres

Two approaches, based on:

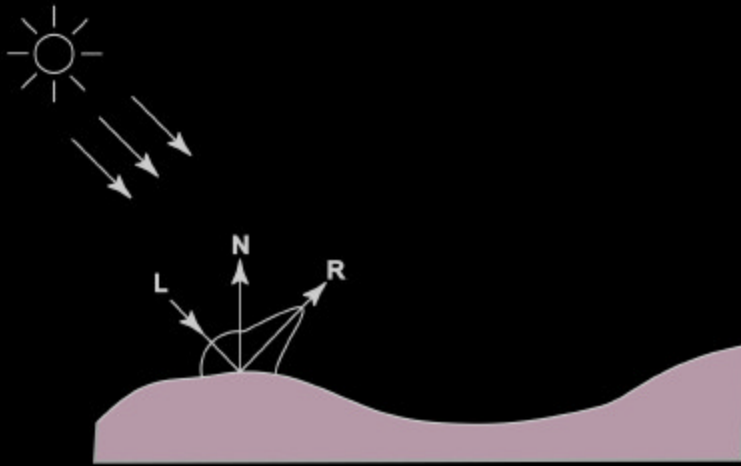
1. Vector quantization (VQ)
2. Singular value decomposition (SVD)

Preprocessing to improve coherence.

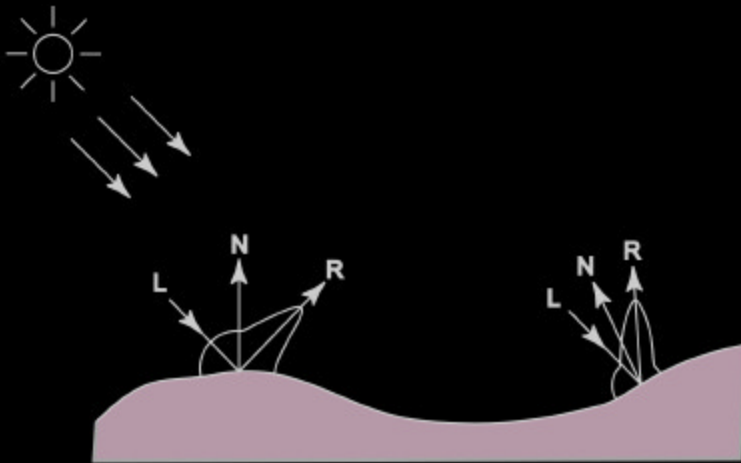


Small set of prototypes

Reflected reparameterization

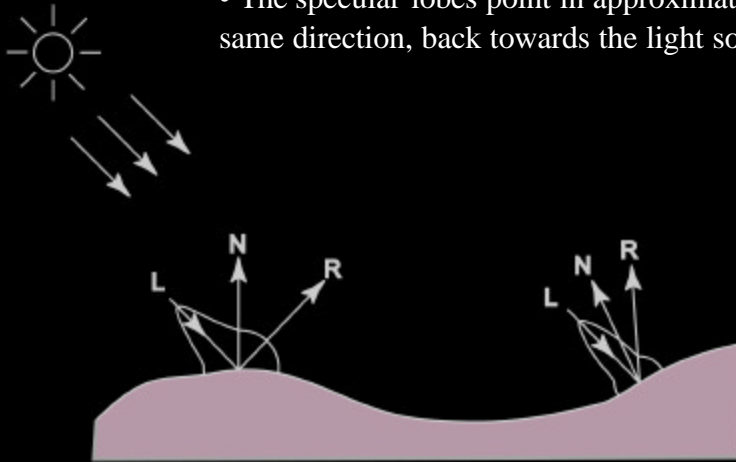


Reflected reparameterization



Reflection reparameterization

- Reflect the lumispheres through their normals
- The specular lobes point in approximately the same direction, back towards the light source.



Reflected reparameterization

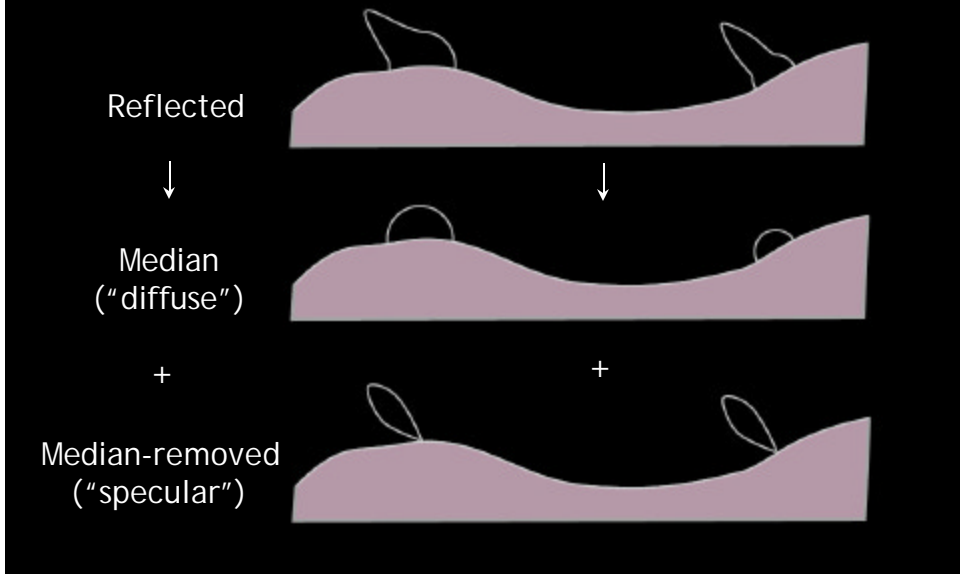
Before



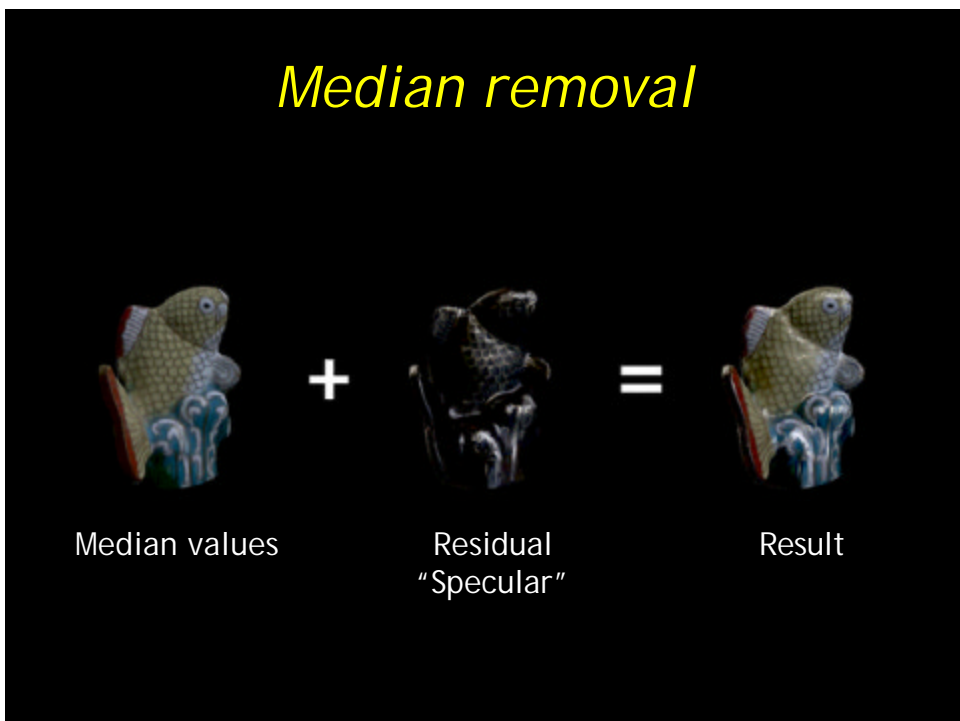
After



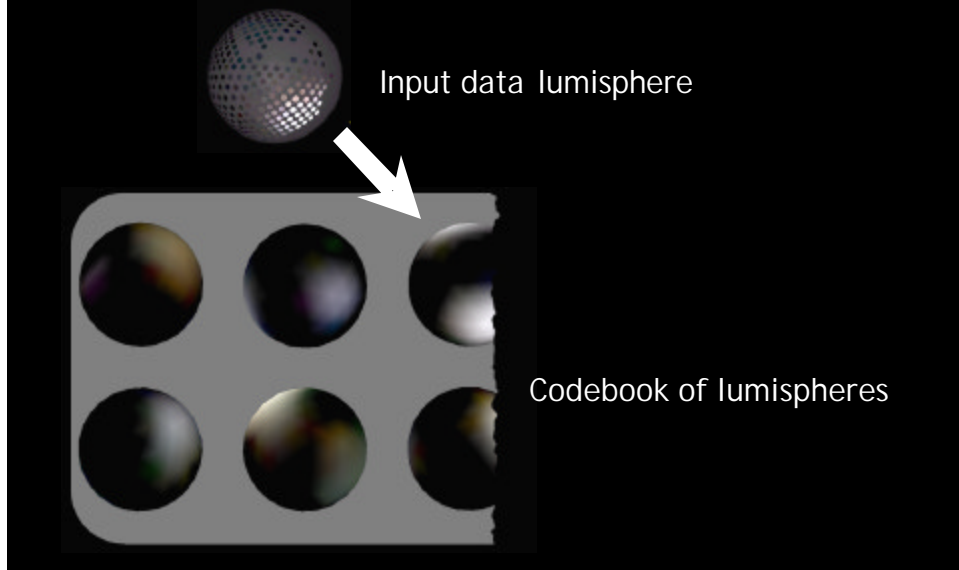
Median removal



Median removal



Function quantization based on vector quantization



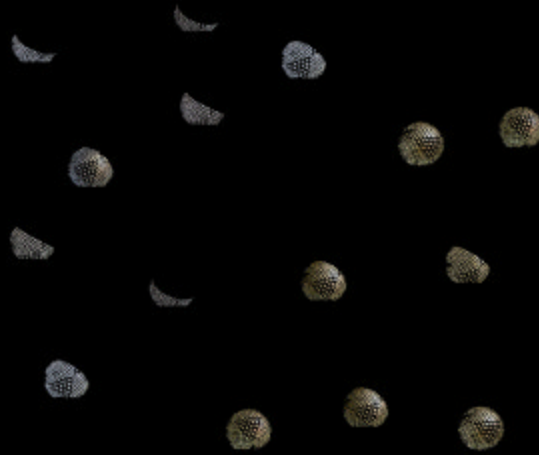
Construct codebook using Lloyd iteration

Iterate until convergence:

1. Assign all data lumispheres to closest codeword, forming clusters.
2. Compute new codeword for each cluster by "cluster-wise" fairing.

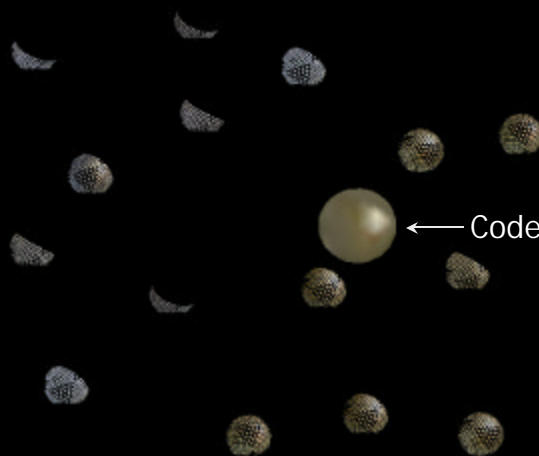
Then split all codewords and start over.

Lloyd iteration



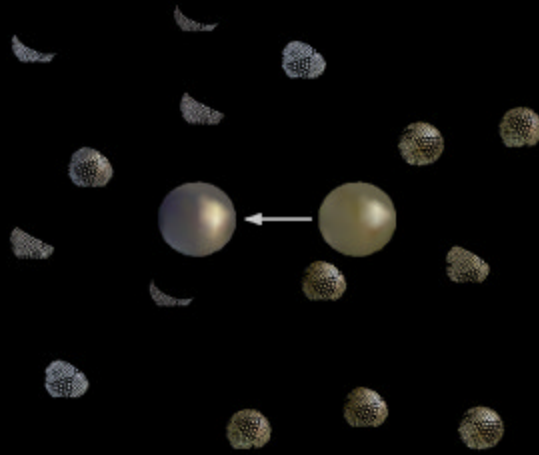
Input data lumispheres

Lloyd iteration



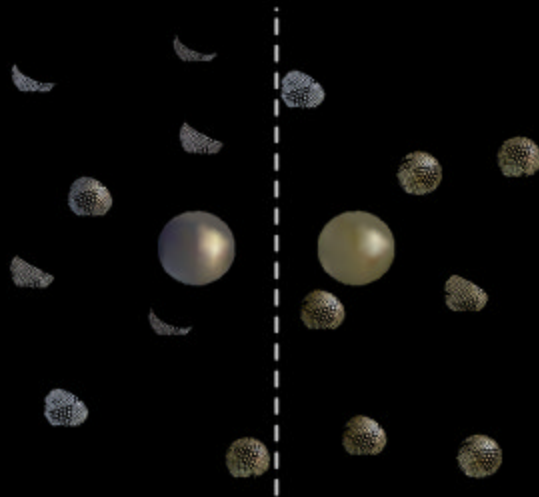
← Codeword

Lloyd iteration



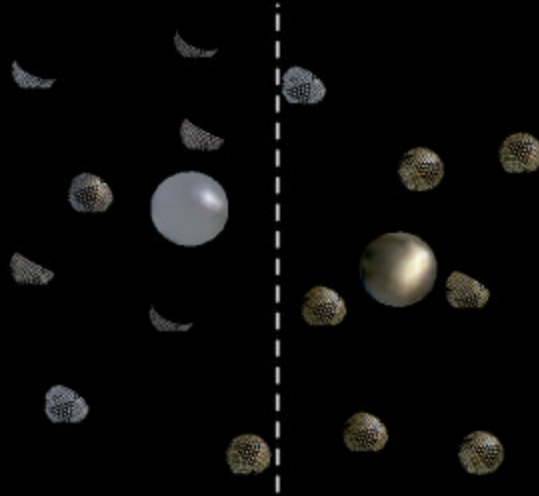
Perturb codewords to create larger codebook

Lloyd iteration



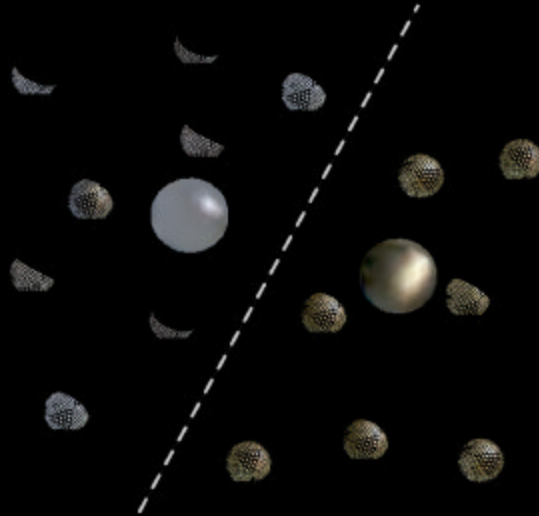
Form clusters around each codeword

Lloyd iteration



Optimize codewords based on clusters

Lloyd iteration

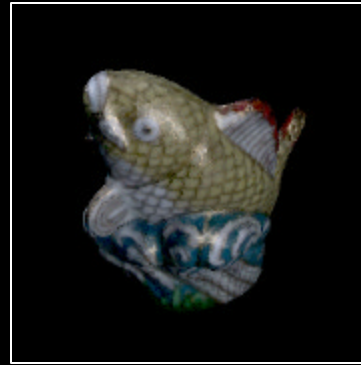


Create new clusters

Function quantization results

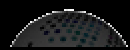


Input photograph

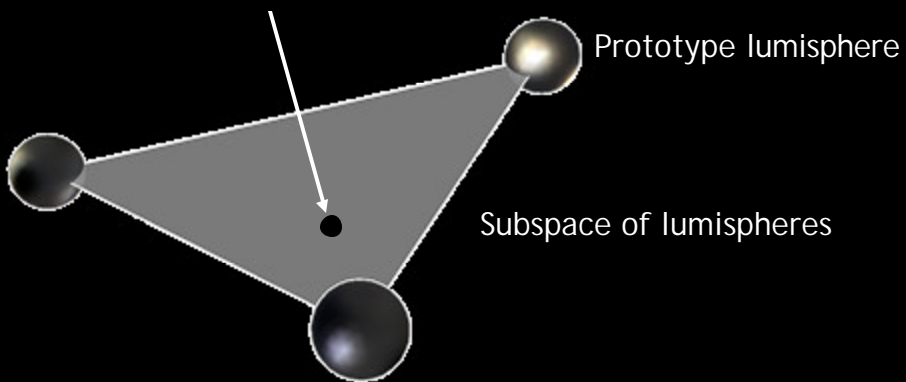


Function quantized
(1010 codewords, 2.6 MB)

Principal function analysis



Input data lumisphere



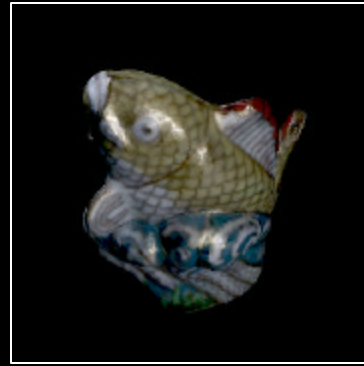
Prototype lumisphere

Subspace of lumispheres

Principal function analysis results



Input photograph



PFA compressed
(Order 5 - 2.5 MB)

Compression comparison



Pointwise fairing
(177 MB)



Function quantization
(2.6 MB)



Principal function analysis (2.5 MB)

Qualitative comparison

- PCA leads to smoother images
- Function quantization introduces artifacts such as jaggies on tail
- Function quantization better preserves colors in highlights and effects of inter-reflections

Comparison with 2-plane light field (uncompressed)



Pointwise-faired
surface light field (177 MB)

Uncompressed
lumigraph / light field (177 MB)

Comparison with 2-plane light field (compressed)

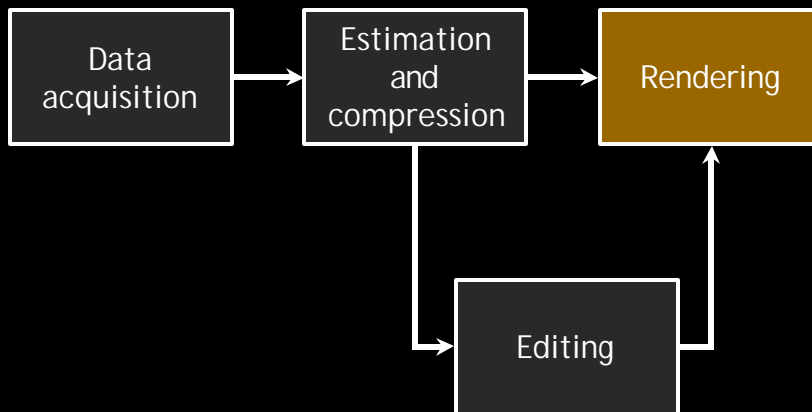


Compressed (PFA)
surface light field (2.5 MB)



Vector-quantized
lumigraph / light field (8.1 MB)

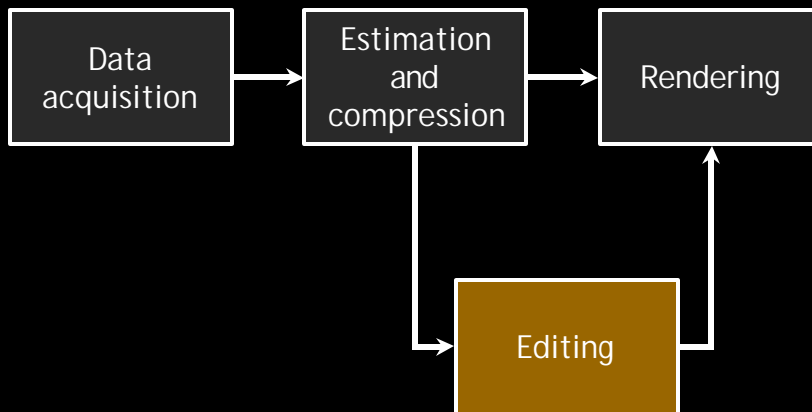
Overview



Interactive renderer screen capture



Overview



Lumisphere filtering

Simple bias function to the values in the lumisphere, making the specular lobes taller and narrower.



Original surface light field



Glossier coat

Rotating the Lighting by rotating the lumispheres...



Original surface light field



Rotated environment

Deformation



Original

Deformed

Deformation

